



---

**III**

**1**

**6**

**BX-100**

**17**

**51**

**I**  
**...586**

.....

.....59

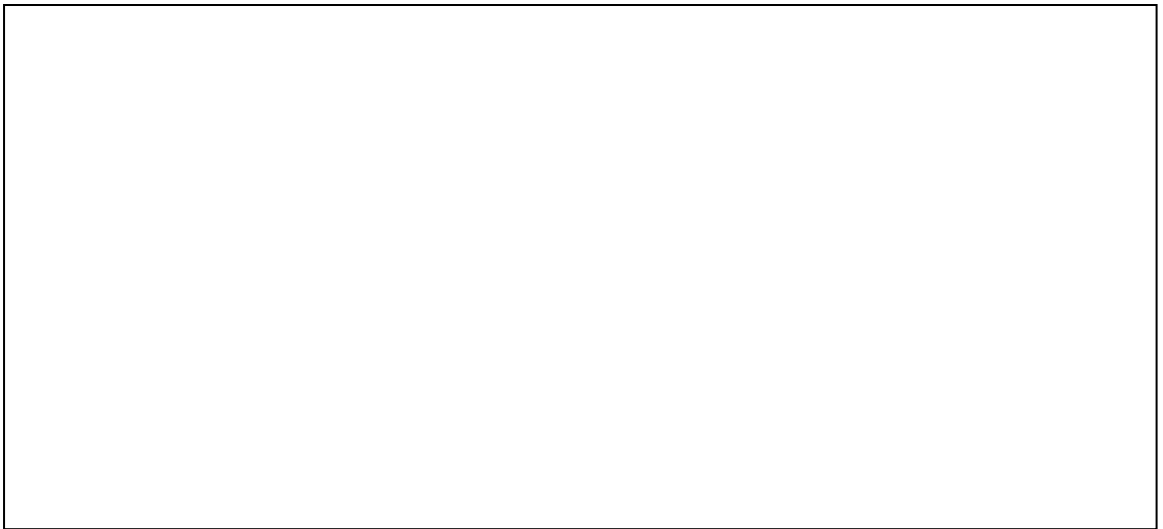
.....61

**616G5 676GL5-JJ** .....62

**G7A** .....64

**G11UD** .....66

**2005-4-25** .....68







---

---

---

---

---

---

████████████████████

---

---





---

---

### 1.3 安全保护功能

---

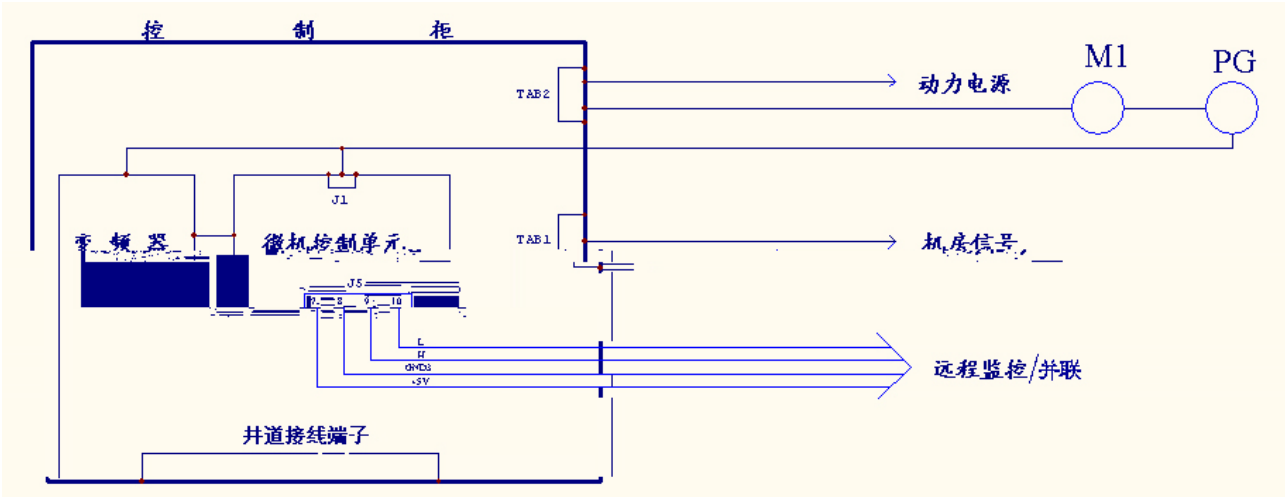
---

### 1.4 可选功能

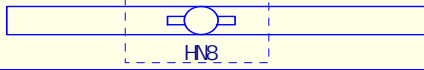
---

---

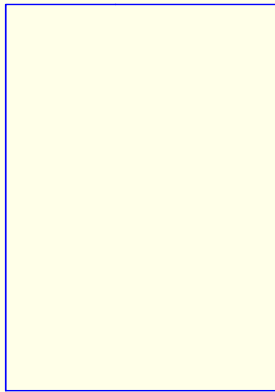
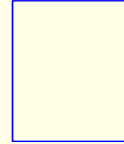
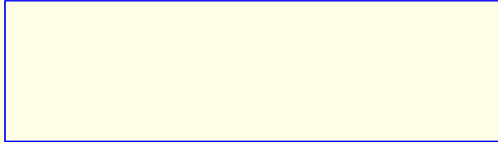
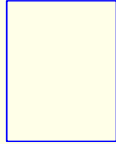
## 2.1 控制系统的组成



FN8



HN8



°		
		°

%	%	%	%	%	%
:	%	:	&	:	'
:	(	L	:		
&	&	&	&	&	&

5%	5&		
%	%	@	)
'			
?	A	6	
&	%	(	H
*	H		((

5%	5&		
%	%	@	)
'			
?	@	N	
&	%	(	H
*	H		((

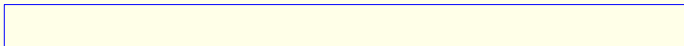
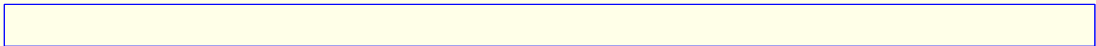
5%	5&		
%	%	@	)
'			
?	?A		
&	%	(	H
*	H		((

5%	5&		
%	%	@	)
'			
?	; A		
&	%	(	H
*	H		((

5%	5&		
%	%	@	)
'			
?	A	7	
&	%	(	H
*	H		((

5%	5&		
%	%	@	)
'			
?	8M		
&	%	(	H
*	H		((

5%	5&		
%	%	@	)
'			
?	>H		
&	%	(	H
*	H		((



7%	1%	J%	K%	B	I'	J'	K'
----	----	----	----	---	----	----	----

H7&

D1



H7%














---



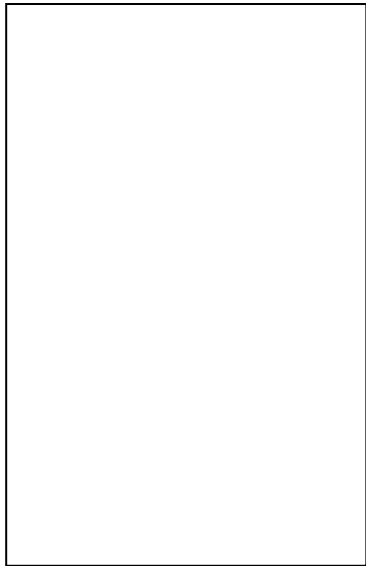








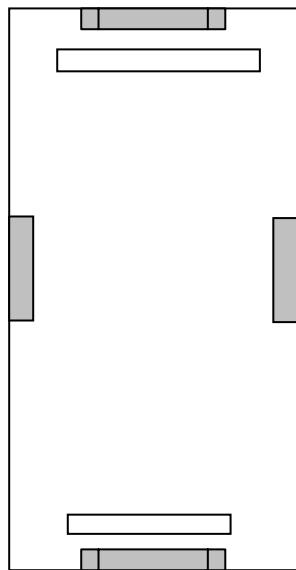












---





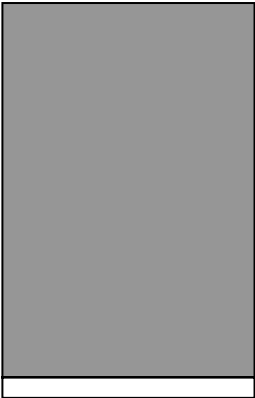
## 2.2 控制系统的安装

---

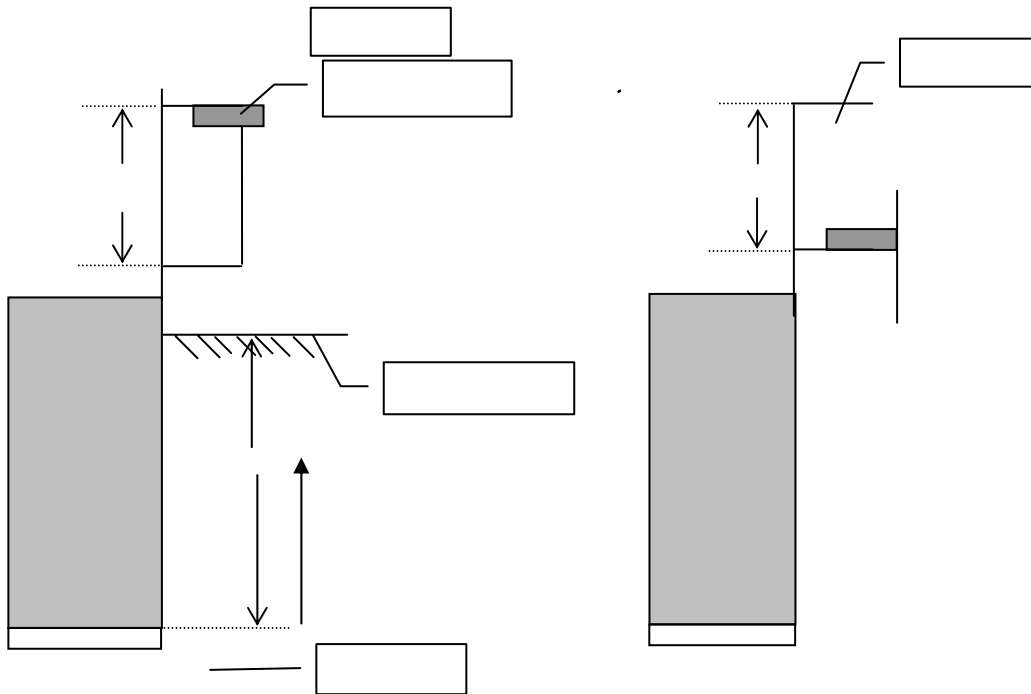


f&E

f&E



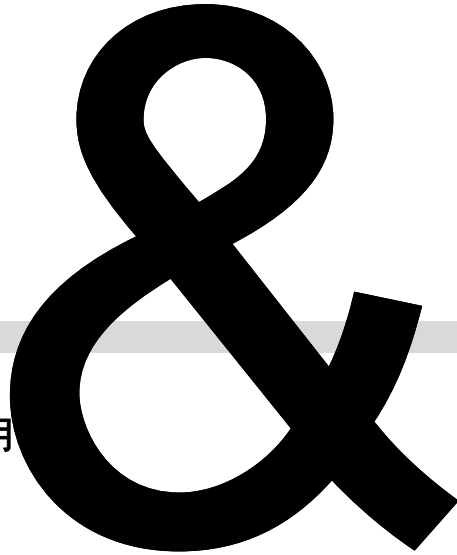


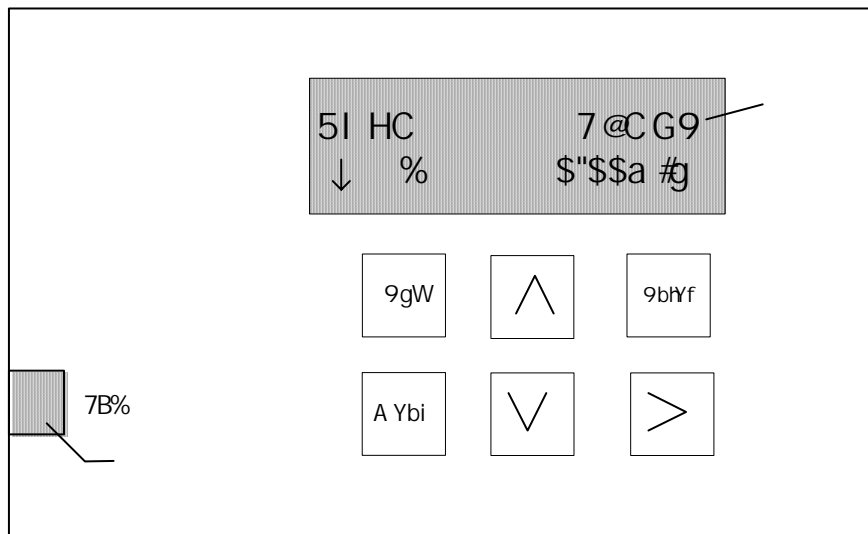
---

# BX-100

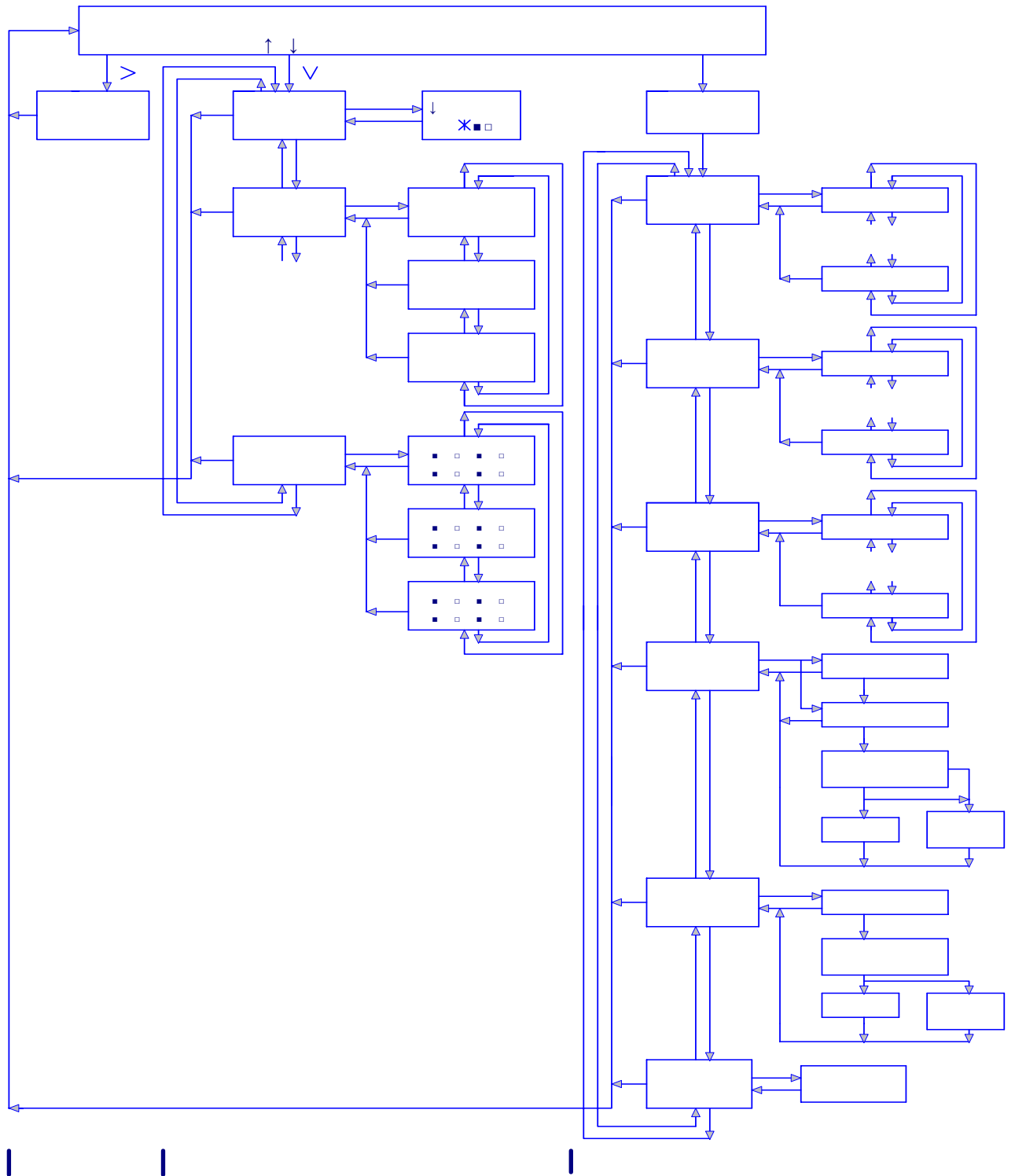
## 3.1 概述



## 3.2 键操作说明



### 3.3 液晶显示流程图及参数说明





INSP ER=10 CLOSE  
↓ 1 0.00m/s

- ▶
- ▶
- ▶
- ▶

—  
—

.....



6@ Vta . C?  
Gmg Vta . C?

- ▶
- ▶

—  
—  
—  
—

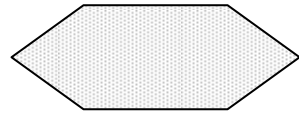
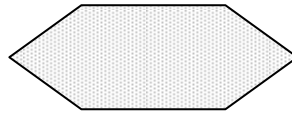
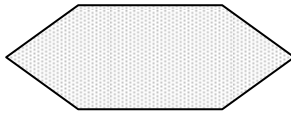
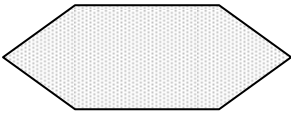


Input Password 0000  
Enter

---



---





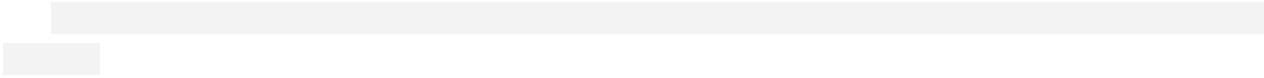


		Call Input		
		Hoistway Data		
		Floor Data		
		Speed Feedback		
		I/O Value		
		Run Report		
		Fault Report		
		Encoder Apprais		
		Input Apprais		
		Software No		
		I/O Input		
		I/O Output		
		I/O Car Data		



		Total Floor	--			
		Homing Floor				
		Set Time	--			
		Open Door Time				
		Open Delay Time				
		Homing Time				
		Start Time				
		Stop Time				
		Fire Floor		—		
		Parking Floor		—		
		Input Type				



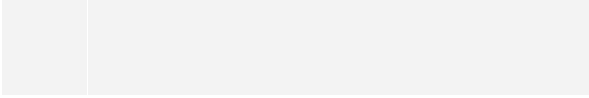


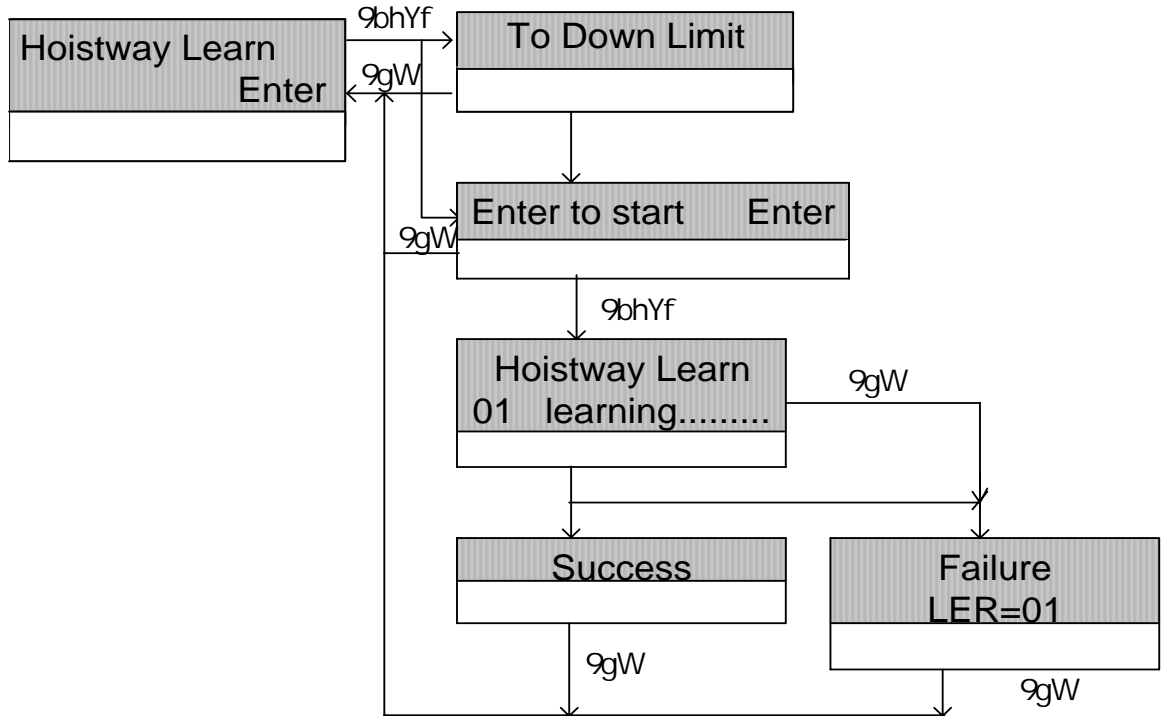
1  $\frac{t \quad t' \% t}{* \$ \% \$ \$ \$}$

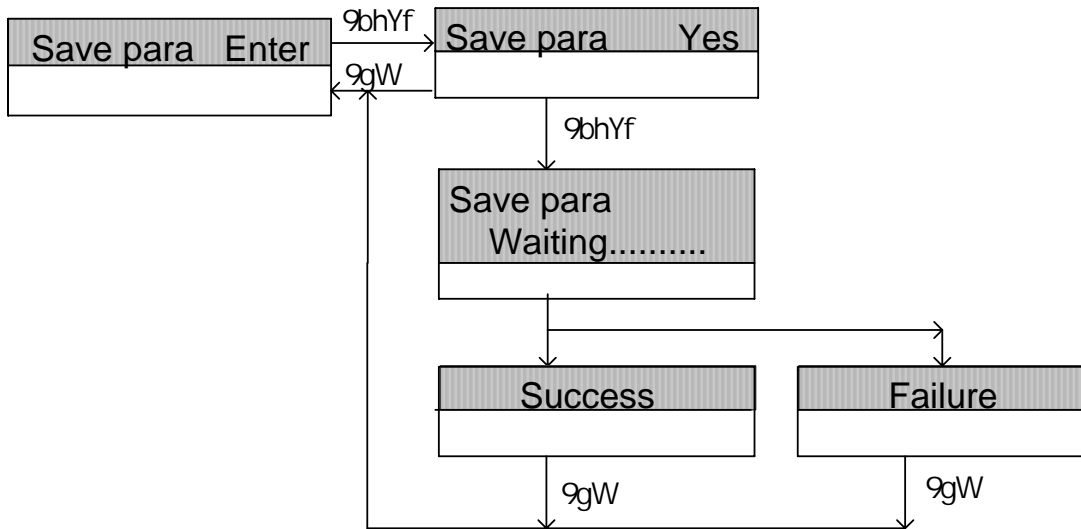
1  $\frac{\% + \$) - \$ ' \% (t \&}{* \$ \% \$ \$ \$ \% )}$  1% \* #



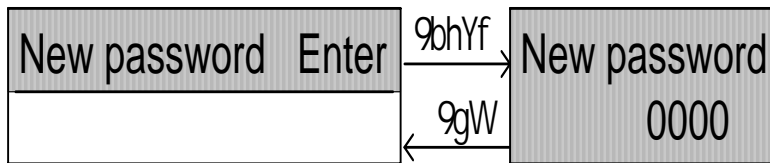
		Door Run Time				
		Factory para				
		Twins Control				
		Far Monitor				
		Two Door Mode				
		Fire Mode				







- 
- 



### 3.4 窗口及操作说明



- 
- 



---

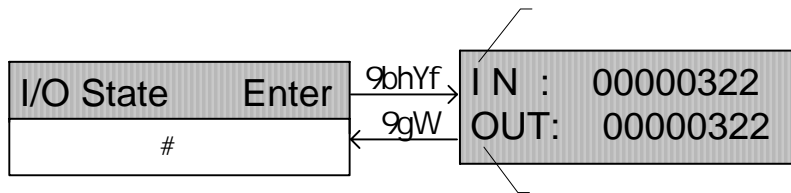
Call Input	Enter

↓	I	S	X	F5
03:*	■	□		

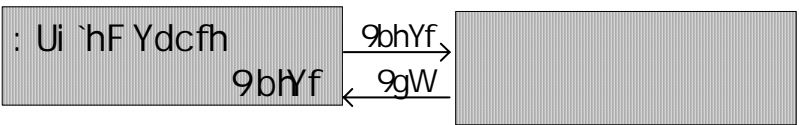
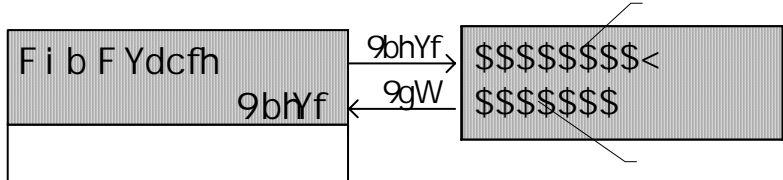
- 
- †
- †
- 
- 

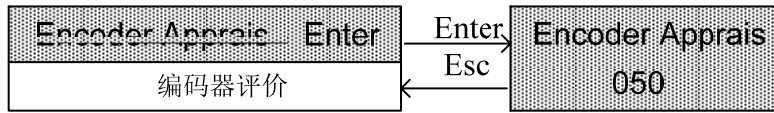
Hoistway Data	Enter





=B 1\$\$\$\$\$' &&ž CI H1\$\$\$\$\$' &&  
 =B 1%\$\$\$\$\$\$%ž CI H1%\$\$\$\$\$\$%\$  
 L\$ L% L& L' L( L) L\* L+ L, L- L%\$ L%%  
 \$ % \$ \$ \$ \$ % \$ % \$ \$ \$  
 L%&L% L%( L%) L%\* L%+ L% L% L&\$ L&% L&& L&'  
 \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$  
 M\$ M% M& M M( M) M\* M+ M, M- M%\$ M%%  
 \$ % \$ \$ \$ \$ % \$ % \$ \$ \$  
 M%&M% M%( M%)  
 \$ \$ \$ \$









---

%

9bhYf

.....

&

General para Enter

HchU : `ccf %&



Homing Floor 1



— —

---

Set Time 00-00-00 00:00



Open Door Time 000s



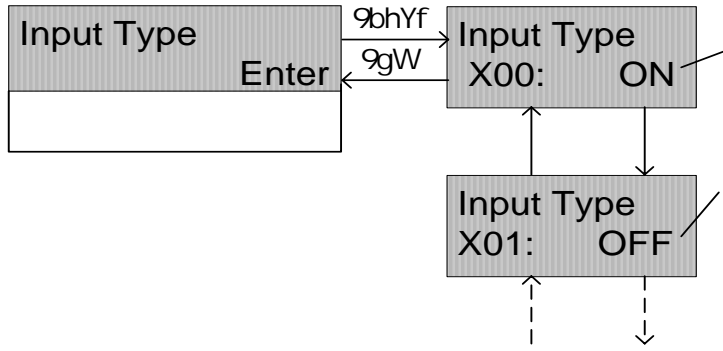
Open Delay Time 000s

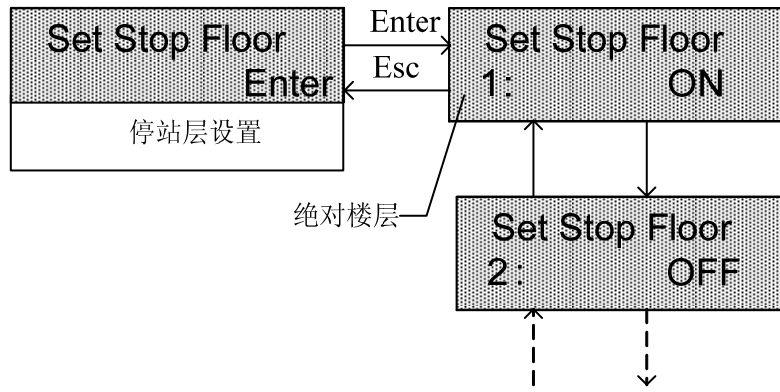


Homing Time 000s

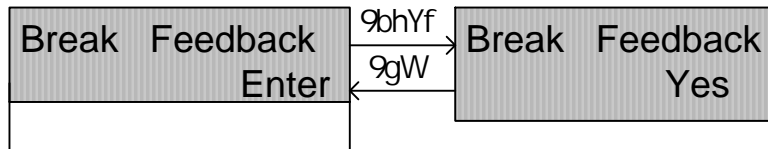
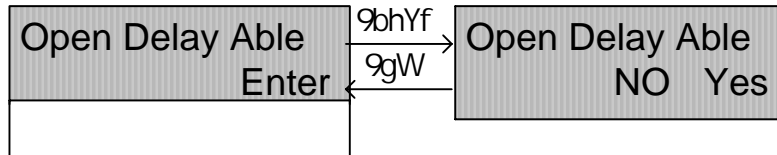




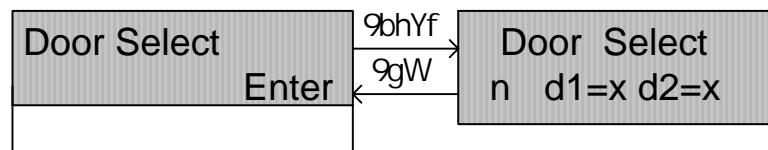




➤  
➤



➤  
➤



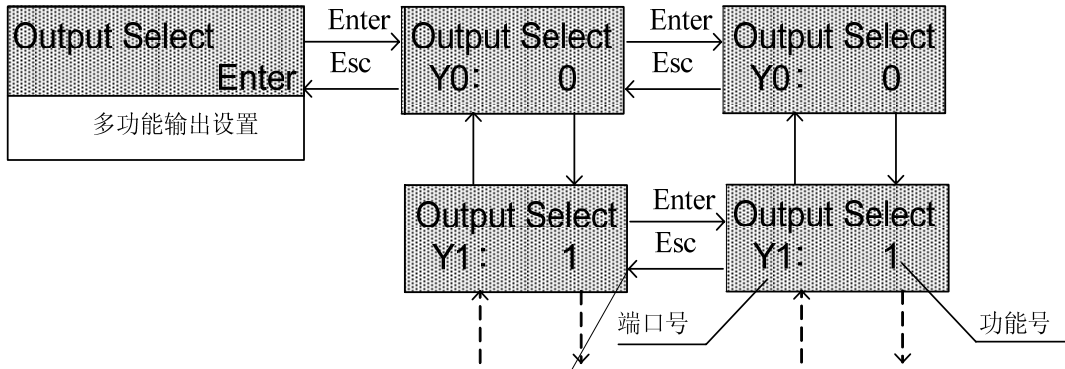


➤  
➤

X0 1 X1

21

➤





---




Runing para  
Enter

- 
- 
- 

Car Speed  
1.60m/s

Motor Speed  
1350rpm

- 
- 

**Pulses**  
**0600**



---

Insp Speed 0.30m

**Leveling Speed**  
**0.03m/s**

**Star Speed**  
**0.00m/s**

**Least Speed**  
**1.00m/s**

- 
- 
- 

Break On Time  
50ms

Break Off Time  
50ms

**Acceleration b1**  
**0.6m/s<sup>2</sup>**

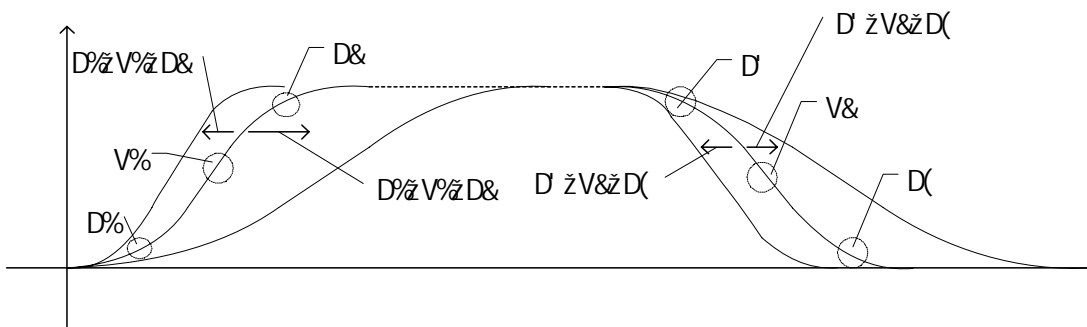
**Deceleration b2**  
**0.6m/ s<sup>2</sup>**

**S Curve P1**  
**0.6m/ s<sup>2</sup>**

**S Curve P2**  
**0.6m/ s<sup>2</sup>**

**S Curve P3**  
**0.6m/ s<sup>2</sup>**

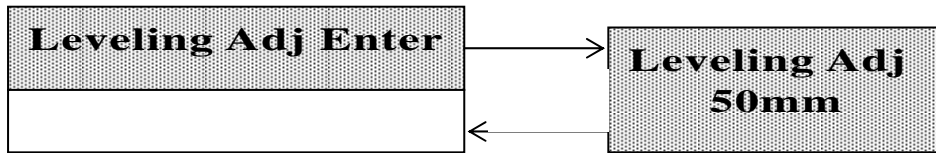
**S Curve P4**  
**0.6m/ s<sup>2</sup>**



---

Zero Speed 0005r

) #



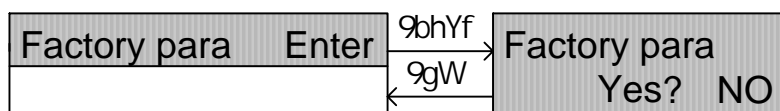
---

Special para Enter

- 
- 
- 

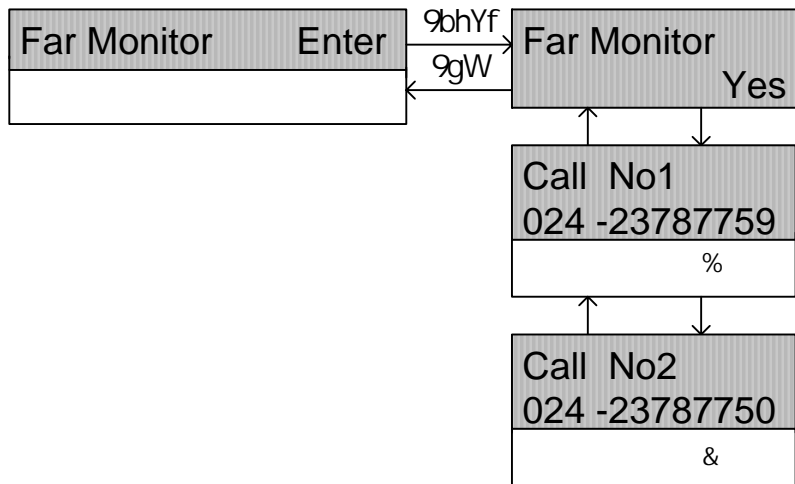
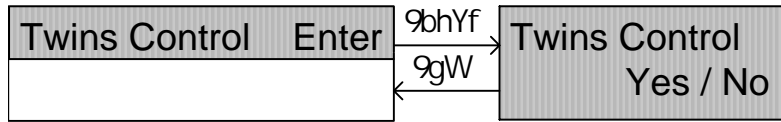
Door Run Time 005s
#

)

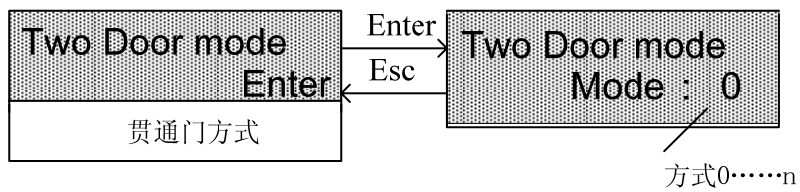


➤  
➤

➤  
➤



➤  
➤  
➤



➤  
➤



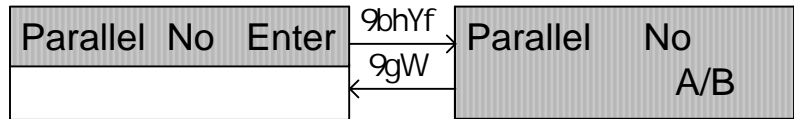
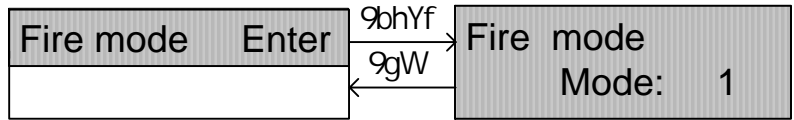
.

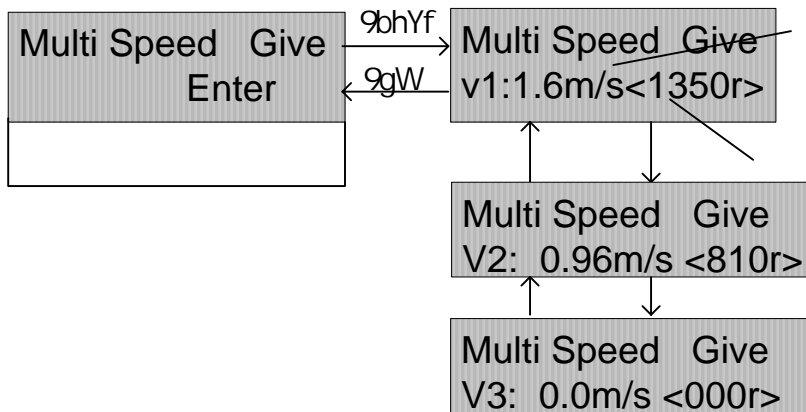
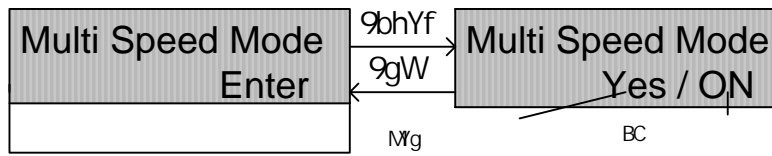
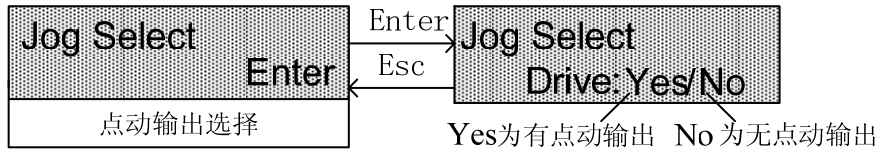


.



.





---




16 If3^ Ö¼Et!LäcLÃâ ó z Ä



Decel Distance
Enter

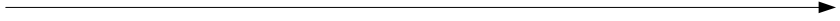


Over Time
Ente

ft








---

## 4.1 通电前的检查



## 4.2 通电和检查

---

---


---

### 4.3 系统参数设定

---

- 
- 
- 

≤ ≤

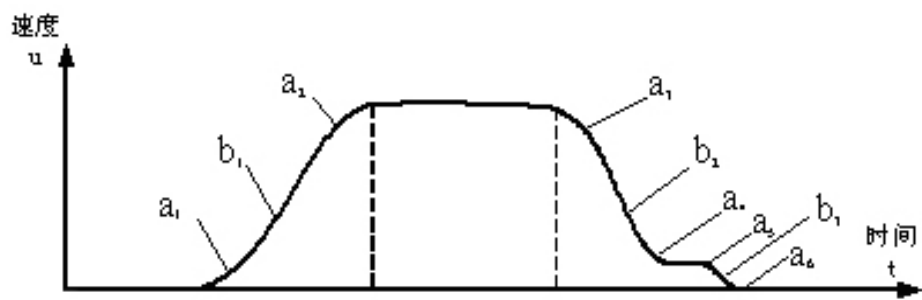

- 
-



---

---

## 4.5 井道自主学习运行



\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_



h%      =  
h%

) #

## 4.8 平层精度的调整

➤

➤

➤

fP&L"

fP&L"

V (I%

V

fP L"

	: I \$&	C :
	: I \$&	CB =

## 4.9 端站安装位置的确认

% \* a#g

&" ) a

---

ž  
&') ± \$"%&

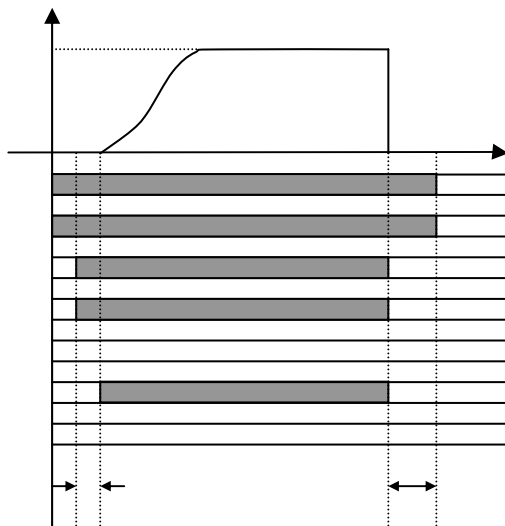
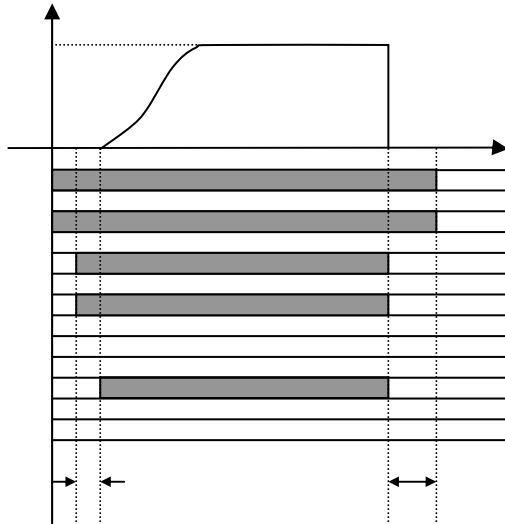
\$" a#g"

ž fl 7

ž ž

---

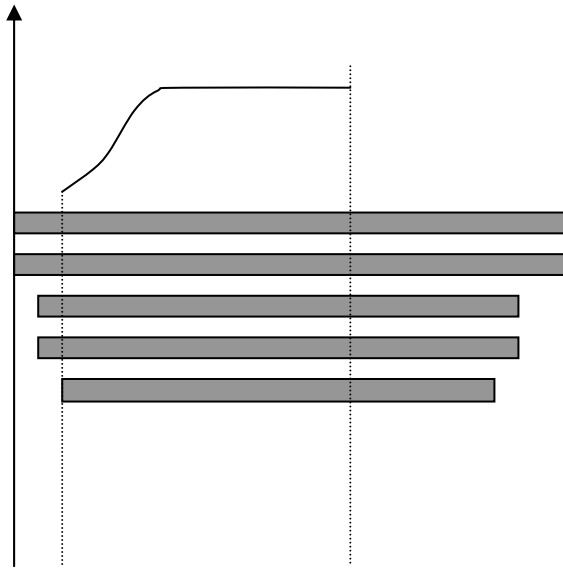
# I





- 
- 
- 
- 

)



- 
-



\*




**616G5 676GL5-JJ**



# G7A

5% \$\$	@78	\$	
5% \$%		&	58J5B798
5% \$&		'	D,
6% \$%		%	
6% \$&		%	
6% \$'		%	
6% \$(		\$	
6& \$%		\$" %	<N 6& \$%09% \$-      9% \$- D,      6& \$%
6& \$'		\$	
6& \$(		%	
7% \$%	%	&")	\$    %\$\$
7% \$&		&")	%\$\$    \$
7% \$'	&	&")	%    CB
7% \$(	&	," \$	%    CB
7& \$%	G	\$" +	
7& \$&	G	\$")	
7& \$'	G	\$" +	
7& \$(	G	\$" +	
7)! \$%		%\$	
7)! \$&	%	\$"')	
8% \$&	&	&\$\$	%    CB
8% \$'	'		&    CB
8% \$(	(	%\$\$	% &    CB
8% \$,	,	%( &)	% & '    CB
8% %+		&\$\$	: >C    CB
9% \$%		' , \$	%J
9% \$&		\$	
9% \$(		)\$	
9% \$)		' , \$	
9% \$*	: 5	)\$	
9% \$-	: A=B	\$	
9& \$%			5

			<N g ]d
9& \$&			5
9& \$'			
9& \$(			\$* \$%K
9& %%			D,
: % \$%	D,	D,	D,
: % \$&	D, D, C	%	
: % \$'	CG	\$	7% \$&
: % \$(	89J	\$	7% \$&
: % \$*	D,	%	D, 1 %Zb #až b1\$Z% a1% ' &
: % \$,	CG	%)	CG : % \$, %\$\$ : % \$-
: % %\$	89J	' \$	: % %\$ 89J : % %\$ : % %%
: % %%	89J	%	
<% \$'	G)	'	'
<% \$(	G*	(	(
<% \$)	G+	)	)
<% \$*	G	:	*
<% \$+	G-	:	+
<% \$,	G%\$	+	,
<% \$-	G%&	*	-
<% %\$	G%&	-	%\$
<& \$%	A% A&	' +	
@! \$(		\$	\$J
@! \$%		)	
@! \$)		%	
@! \$+		%	
C% \$%		)	
C% \$'	#		

# G11UD

: \$&		%	
: \$'	%	) \$<n	
: \$(	%	) \$<n	
: \$)	%	' , \$J	
: \$*	%	' , \$J	
: \$+	%	' ") G	
: \$,	%	\$" \$%G	
: %%			%\$%
: %&		\$" ) a] b	C@%
: %)		) \$<n	
: %*		\$ <n	
: &'		\$" (<n	
: &(<		\$" ' <n	
: &)		\$" %<n	
: &*		% ?<n	
: &+		\$	
: ' *	' \$Fm	\$	
: (\$	%	&\$	
: (%	%	&\$	
9\$%	L%	\$	
9\$&	L&	%	
9\$'	L'	&	
9\$(	L(	)	
9\$)	L)	)	
9\$-	L-	-	
9\$&	&	' ") g	
9\$%	&	' ") g	
9\$&	'	' ") g	
9\$%	'	&' ) g	
9\$%	(	% g	
9&\$	M%	+	
9&%	M&	%	
9&)	M)	\$	
9'	fIC@L	%	
9 (	fIC@L	D\$* x \$')	
<9%		%	
9 )	fIC@L	\$' & G	
7%&	\$	\$<n	

7C)	%	, <n	
7C*	&	, <n	
7C+	'	' <n	
7%\$	*	' \$<n	
7%%	+	) \$<n	
D\$%		†	
D\$&		†	
D\$'		†	
D\$*		†	
D\$-			
C\$%		%	%
C\$&		\$" \$\$\$	
C\$'		†	
C\$(	5GF D fl t	&\$	
C\$)	5GF =	\$" %	
C\$*		\$" \$'\$	
C\$+	5GF D %	)	
C\$,	5GF D &	%\$	
C\$-	5GF D fl t	&\$	
C\$%		\$" \$\$) G	
C%&	-	\$ %	
C%G	G %	&\$	G
C%G	G (	&\$	G
C%G	G )	&\$	G
C%G	G *	&\$	G
C%G	G +	%	G
C&\$	G ,	%	G
C&%	G -	' \$	G
C&&	G %\$	' \$	G
C +		\$" \$	
C ,		\$" '	

× \_\_\_\_\_  
Of #a] b]

2005-4-25



' 9F& % %  
( @9F&% &a#g  
) @9F&& &a#g  
\*"

6fYU_ 7\YW_ H] aY &\$\$\$ag

6YYd XY` Um h] aY ) \$\$ag

@lad cZZ h]aY  
%a]b

6fYU\_ Yff h]aYf  
)

M7 Yff h]aYf  
)

M7

GY YWn cfXYf AU  
,

NYfc H]aY  
' \$\$ag